W_1 -Curvature Tensor within the framework of Lorentzian α -Sasakian Manifold

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Abstract. The objective of this paper is to investigate the curvature properties of Lorentzian α -Sasakian manifolds under specific geometric conditions. In particular, we examine these manifolds when they satisfy the following conditions: ζ -W₁-flatness, φ -W₁-semi-symmetry, and the vanishing of certain curvature operators, specifically W₁ · Q = 0 and W₁ · R = 0. Through our analysis, we derive several interesting results regarding the geometric structure and behavior of these manifolds under the given conditions.

Key words and Phrases: Almost contact manifolds, trans-Sasakian manifolds, Lorentzian α -Sasakian manifolds, φ -symmetric, φ -semisymmetric.

1. INTRODUCTION

- S. Tanno classified linked almost contact metric manifolds with the largest dimension automorphism groups in [1]. For such a manifold, the sectional curvature of plane sections containing the vector field ζ is constant, denoted by c. He identified three distinct classes for these manifolds:
 - (i) Homogeneous normal contact Riemannian manifolds when c > 0
 - (ii) Global Riemannian products of a line or a circle with a Kähler manifold of constant holomorphic sectional curvature when c=0,

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(iii) Warped product spaces when c < 0.

It is well established that manifolds in class (i) are characterized by their ability to admit a Sasakian structure. In the Gray-Hervella classification of almost Hermitian manifolds [2], the class W_4 is closely associated with locally conformal Kähler manifolds [3]. When the product manifold $M \times R$ belongs to the W_4 class, the almost contact metric structure on the manifold M is referred to as a trans-Sasakian structure [4, 5]. The class $C_6 \oplus C_5$ [6] corresponds to trans-Sasakian structures of type (α, β) . Moreover, the local nature of the two subclasses of trans-Sasakian structures, namely C_5 and C_6 , is well defined in [6].

It is noted that trans-Sasakian structures of types (0,0), $(0,\beta)$, and $(\alpha,0)$ correspond to cosymplectic [5], β -Kenmotsu [7], and α -Sasakian [7] structures, respectively. As shown in [8], trans-Sasakian structures are generalized quasi-Sasakian structures [7]. Consequently, trans-Sasakian structures encompass a wide range of generalized quasi-Sasakian structures. Following this, Yildiz and Murathan introduced Lorentzian α -Sasakian manifolds in [9].

An almost contact metric structure $(\varphi, \zeta, \eta, g)$ on a manifold M is referred to as a trans-Sasakian structure [4] if the product manifold $(M \times \mathbb{R}, \mathcal{J}, \mathcal{G})$ belongs to the class W_4 [2]. Here, \mathcal{J} denotes the almost complex structure on $M \times \mathbb{R}$, defined as follows

$$\mathcal{J}(\mathcal{F}, f\frac{d}{dt}) = (\varphi \mathcal{F} - f\zeta, \eta(\mathcal{F})\frac{d}{dt}),$$

for all vector field \mathcal{F} on M and any smooth function f on $M \times \mathbb{R}$, with \mathcal{G} being the product metric on $M \times \mathbb{R}$, this can be described by the following condition [10]

$$(\nabla_{\mathcal{F}}\varphi)\mathcal{G} = \alpha(g(\mathcal{F},\mathcal{G})\zeta - \eta(\mathcal{G})\mathcal{F}) + \beta(g(\varphi\mathcal{F},\mathcal{G})\zeta - \eta(\mathcal{G})\varphi\mathcal{F}), \tag{1}$$

for some smooth functions α and β on M, the trans-Sasakian structure is said to be of type (α, β) .

From equation (1), it follows that

$$\nabla_{\mathcal{F}}\zeta = -\alpha\varphi\mathcal{F} + \beta(\mathcal{F} - \eta(\mathcal{F})\zeta),\tag{2}$$

$$(\nabla_{\mathcal{F}}\eta)(\mathcal{G}) = -\alpha g(\varphi \mathcal{F}, \mathcal{G}) + \beta g(\varphi \mathcal{F}, \varphi \mathcal{G}). \tag{3}$$

More generally, the concept of an α -Sasakian structure [7] can be defined as follows

$$(\nabla_{\mathcal{F}}\varphi)\mathcal{G} = \alpha(g(\mathcal{F},\mathcal{G})\zeta - \eta(\mathcal{G})\mathcal{F}),\tag{4}$$

where α is a non-zero constant. From this condition, it can be easily deduced that

$$\nabla_{\mathcal{F}}\zeta = -\alpha\varphi\mathcal{F},\tag{5}$$

$$(\nabla_{\mathcal{F}}\eta)(\mathcal{G}) = -\alpha g(\varphi \mathcal{F}, \mathcal{G}). \tag{6}$$

Thus, $\beta=0$, meaning a trans-Sasakian structure of type (α,β) with α as a non-zero constant is always an α -Sasakian structure [7, 11]. When $\alpha=1$, an α -Sasakian manifold becomes a Sasakian manifold. Marrero [12] explored the relationship between trans-Sasakian, α -Sasakian, and β -Kenmotsu structures.

 W_1 -curvature tensor [13] is defined as

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{H} = R(\mathcal{F}, \mathcal{G})\mathcal{H} + \frac{1}{n-1}[S(\mathcal{G}, \mathcal{H})\mathcal{F} - S(\mathcal{F}, \mathcal{H})\mathcal{G}], \tag{7}$$

where R and S represent the curvature tensor and Ricci tensor of the manifold, respectively.

K. Kenmotsu [14] introduced a new class of almost contact Riemannian manifolds, known as Kenmotsu manifolds. He investigated the fundamental properties of their local structure. Kenmotsu manifolds are locally isometric to warped product spaces with a one-dimensional base and a K \ddot{a} hler fiber. Kenmotsu showed that if a Kenmotsu manifold satisfies the condition $R(\mathcal{F},\mathcal{G})\mathcal{H}=0$, then the manifold has a constant negative curvature of -1, where R is the Riemannian curvature tensor and $R(\mathcal{F},\mathcal{G})\mathcal{H}$ represents the derivative of the tensor algebra at each point of the tangent space. It is well known that odd-dimensional spheres admit Sasakian structures, whereas odd-dimensional hyperbolic spaces do not; instead, they admit Kenmotsu structures. Kenmotsu manifolds are normal almost contact Riemannian manifolds. Various geometric properties of Kenmotsu manifolds, as well as several curvature structures including the Bochner curvature tensor [15], M-Projective curvature tensor [16] etc., have been the subject of extensive investigation in recent years [17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31]. Building upon these contributions, the present study is devoted to a detailed examination of the W_1 -curvature tensor in the setting of Lorentzian α -Sasakian manifolds, following the foundational framework outlined in [9].

2. PRELIMINARIES

A (2n+1)-dimensional smooth manifold M is termed a Lorentzian α -Sasakian manifold if it possesses a (1,1)-tensor field φ , a vector field ζ , a 1-form η , and a Lorentzian metric q that satisfy the following conditions [9]:

$$\varphi^2 = I + \eta \otimes \zeta, \tag{8}$$

$$\varphi^{2} = I + \eta \otimes \zeta, \tag{8}$$

$$\eta(\zeta) = -1, \varphi(\zeta) = 0, \eta \circ \varphi = 0, \tag{9}$$

$$g(\mathcal{F},\zeta) = \eta(\mathcal{F}),$$
 (10)

$$g(\varphi \mathcal{F}, \varphi \mathcal{G}) = g(\mathcal{F}, \mathcal{G}) + \eta(\mathcal{F})\eta(\mathcal{G}), \tag{11}$$

$$(\nabla_{\mathcal{F}}\varphi)\mathcal{G} = \alpha \{ q(\mathcal{F}, \mathcal{G})\zeta + \eta(\mathcal{G})\mathcal{F} \}, \tag{12}$$

for all $\mathcal{F}, \mathcal{G} \in TM$. Also a Lorentzian α -Sasakian manifold M satisfies the following [9]

$$\nabla_{\mathcal{F}}\zeta = \alpha\varphi\mathcal{F},\tag{13}$$

$$(\nabla_{\mathcal{F}}\eta)(\mathcal{G}) = \alpha q(\mathcal{F}, \varphi \mathcal{G}), \tag{14}$$

where ∇ denotes the covariant differentiation operator associated with the Lorentzian metric g, and α is a constant.

Additionally, a Lorentzian α -Sasakian manifold M satisfies the following relations [9]:

$$\eta(R(\mathcal{F},\mathcal{G})\mathcal{H}) = \alpha^2 \{ g(\mathcal{G},\mathcal{H})\eta(\mathcal{F}) - g(\mathcal{F},\mathcal{H})\eta(\mathcal{G}) \}, \tag{15}$$

$$R(\mathcal{F}, \mathcal{G})\zeta = \alpha^2 \{ \eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G} \}, \tag{16}$$

$$R(\zeta, \mathcal{F})\mathcal{G} = \alpha^2 \{ g(\mathcal{F}, \mathcal{G})\zeta - \eta(\mathcal{G})\mathcal{F} \}, \tag{17}$$

$$R(\zeta, \mathcal{F})\zeta = \alpha^2 \{ \eta(\mathcal{F})\zeta + \mathcal{F} \}, \tag{18}$$

$$S(\mathcal{F},\zeta) = 2n\alpha^2 \eta(\mathcal{F}),\tag{19}$$

$$Q\zeta = 2n\alpha^2\zeta,\tag{20}$$

$$S(\zeta, \zeta) = -2n\alpha^2,\tag{21}$$

for any vector fields $\mathcal{F}, \mathcal{G}, \mathcal{H}$, where S is the Ricci curvature and \mathcal{Q} is the Ricci operator, defined by the relation $S(\mathcal{F}, \mathcal{G}) = g(\mathcal{QF}, \mathcal{G})$.

Definition 2.1. A Lorentzian α -Sasakian manifold M is referred to as η -Einstein if its Ricci tensor S takes the following form:

$$S(\mathcal{F}, \mathcal{G}) = \lambda_1 q(\mathcal{F}, \mathcal{G}) + \lambda_2 \eta(\mathcal{F}) \eta(\mathcal{G}), \tag{22}$$

for any vector fields \mathcal{F}, \mathcal{G} , where λ_1 and λ_2 are functions on M. If $\lambda_1 = 0$, then M is classified as a special η -Einstein manifold.

3. W_1 -FLAT LORENTZIAN α -SASAKIAN MANIFOLD

In this section, we study W_1 -flat in Lorentzian α -Sasakian manifold.

Definition 3.1. A Lorentzian α -Sasakian manifold is said to be W_1 -flat if

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{H} = 0, \tag{23}$$

for any vector fields \mathcal{F}, \mathcal{G} and \mathcal{H} on M.

 W_1 -curvature tensor [13, 32] is defined as

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{H} = R(\mathcal{F}, \mathcal{G})\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G}, \mathcal{H})\mathcal{F} - S(\mathcal{F}, \mathcal{H})\mathcal{G}], \tag{24}$$

Using Equation (23) in (24), we have

$$R(\mathcal{F}, \mathcal{G})\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G}, \mathcal{H})\mathcal{F} - S(\mathcal{F}, \mathcal{H})\mathcal{G}] = 0.$$
 (25)

Replacing \mathcal{F} by ζ in (25) we get

$$R(\zeta, \mathcal{G})\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G}, \mathcal{H})\zeta - S(\zeta, \mathcal{H})\mathcal{G}] = 0.$$
 (26)

Using Equations (17) and (19) in (26), we have

$$\alpha^{2} \{ g(\mathcal{G}, \mathcal{H}) \zeta - \eta(\mathcal{H}) \mathcal{G} \} + \frac{1}{(n-1)} [S(\mathcal{G}, \mathcal{H}) \zeta - 2n\alpha^{2} \eta(\mathcal{H}) \mathcal{G}] = 0,$$

$$\alpha^2 g(\mathcal{G}, \mathcal{H}) \zeta - \alpha^2 \eta(\mathcal{H}) \mathcal{G} + \frac{1}{(n-1)} S(\mathcal{G}, \mathcal{H}) \zeta - \frac{2n}{n-1} \alpha^2 \eta(\mathcal{H}) \mathcal{G} = 0,$$

$$\frac{1}{(n-1)}S(\mathcal{G},\mathcal{H})\zeta = \frac{2n}{n-1}\alpha^2\eta(\mathcal{H})\mathcal{G} + \alpha^2\eta(\mathcal{H})\mathcal{G} - \alpha^2g(\mathcal{G},\mathcal{H})\zeta,$$
$$S(\mathcal{G},\mathcal{H})\zeta = -(n-1)\alpha^2g(\mathcal{G},\mathcal{H})\zeta + (3n-1)\alpha^2\eta(\mathcal{H})\mathcal{G}.$$

Taking inner product with ζ , we get

$$S(\mathcal{G}, \mathcal{H}) = -(n-1)\alpha^2 q(\mathcal{G}, \mathcal{H}) + (1-3n)\alpha^2 \eta(\mathcal{G})\eta(\mathcal{H}). \tag{27}$$

Hence from the above discussion, we state the following theorem.

Theorem 3.1. If a Lorentzian α -Sasakian manifold satisfying W_1 -flat condition then the manifold is an η -Einstein manifold.

4. $\zeta - W_1$ -FLAT LORENTZIAN α -SASAKIAN MANIFOLD

In this section, we study $\zeta - W_1$ -flat in Lorentzian α -Sasakian manifold.

Definition 4.1. A Lorentzian α -Sasakian manifold is said to be $\zeta - W_1$ -flat if [33]

$$W_1(\mathcal{F}, \mathcal{G})\zeta = 0, \tag{28}$$

for any vector fields \mathcal{F}, \mathcal{G} on M.

 W_1 -curvature tensor [13] is defined as

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{H} = R(\mathcal{F}, \mathcal{G})\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G}, \mathcal{H})\mathcal{F} - S(\mathcal{F}, \mathcal{H})\mathcal{G}], \tag{29}$$

Replacing \mathcal{H} by ζ in (29), we get

$$W_1(\mathcal{F}, \mathcal{G})\zeta = R(\mathcal{F}, \mathcal{G})\zeta + \frac{1}{(n-1)}[S(\mathcal{G}, \zeta)\mathcal{F} - S(\mathcal{F}, \zeta)\mathcal{G}]. \tag{30}$$

By using (28) in (30), we get

$$R(\mathcal{F}, \mathcal{G})\zeta + \frac{1}{(n-1)}[S(\mathcal{G}, \zeta)\mathcal{F} - S(\mathcal{F}, \zeta)\mathcal{G}] = 0.$$
 (31)

By virtue of (16), (19) in (31) and on simplification, we obtain

$$\alpha^{2} \{ \eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G} \} + \frac{1}{(n-1)} [2n\alpha^{2}\eta(\mathcal{G})\mathcal{F} - 2n\alpha^{2}\eta(\mathcal{F})\mathcal{G}] = 0, \tag{32}$$

$$\{\eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G}\} + \frac{2n}{n-1}\{\eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G}\} = 0,$$

$$\frac{(3n-1)}{(n-1)} \{ \eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G} \} = 0,$$

$$\{\eta(\mathcal{G})\mathcal{F} - \eta(\mathcal{F})\mathcal{G}\} = 0. \tag{33}$$

Putting $\mathcal{F} = \zeta$ and $\mathcal{G} = \mathcal{QG}$ in (33), we get

$$\{\eta(\mathcal{QG})\zeta - \eta(\zeta)\mathcal{QG}\} = 0, \tag{34}$$

$$QG = -2n\alpha^2 \eta(G)\zeta,$$

$$S(\mathcal{G}, \mathcal{H}) = -2n\alpha^2 \eta(\mathcal{G})\eta(\mathcal{H}). \tag{35}$$

Hence from above discussion, we state the following theorem:

Theorem 4.1. If a Lorentzian α -Sasakian manifold satisfying ζ - W_1 -flat condition then the Lorentzian α -Sasakian manifold is a special type of η -Einstein manifold.

5. $\varphi - W_1$ -SEMI-SYMMETRIC CONDITION IN LORENTZIAN α -SASAKIAN MANIFOLD

In this section, we study $\varphi - W_1$ -semi-symmetric condition in Lorentzian α -Sasakian manifold.

Definition 5.1. A Lorentzian α -Sasakian manifold is said to be $\varphi - W_1$ - semi-symmetric if [34]

$$W_1(\mathcal{F}, \mathcal{G}) \cdot \varphi = 0, \tag{36}$$

for any vector fields \mathcal{F}, \mathcal{G} on M.

Now, (36) turns into

$$(\mathcal{W}_1(\mathcal{F},\mathcal{G})\cdot\varphi)\mathcal{H} = \mathcal{W}_1(\mathcal{F},\mathcal{G})\varphi\mathcal{H} - \varphi\mathcal{W}_1(\mathcal{F},\mathcal{G})\mathcal{H} = 0. \tag{37}$$

From Equation (24), we get

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{H} = R(\mathcal{F}, \mathcal{G})\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G}, \mathcal{H})\mathcal{F} - S(\mathcal{F}, \mathcal{H})\mathcal{G}]. \tag{38}$$

Replace \mathcal{H} by $\varphi \mathcal{H}$ in (38), we obtain

$$W_1(\mathcal{F}, \mathcal{G})\varphi \mathcal{H} = R(\mathcal{F}, \mathcal{G})\varphi \mathcal{H} + \frac{1}{(n-1)} [S(\mathcal{G}, \varphi \mathcal{H})\mathcal{F} - S(\mathcal{F}, \varphi \mathcal{H})\mathcal{G}].$$
(39)

Making use of (38) and (39) in (37) and on simplification, we get

$$R(\mathcal{F},\mathcal{G})\varphi\mathcal{H} + \frac{1}{(n-1)}[S(\mathcal{G},\varphi\mathcal{H})\mathcal{F} - S(\mathcal{F},\varphi\mathcal{H})\mathcal{G}] - \varphi(R(\mathcal{F},\mathcal{G})\mathcal{H}) + \frac{1}{(n-1)}[S(\mathcal{G},\mathcal{H})\mathcal{F} - S(\mathcal{F},\mathcal{H})\mathcal{G}]) = 0. \quad (40)$$

Putting $\mathcal{F} = \zeta$ in (40) and by virtue of (17),(19) and on simplification, we obtain

$$\alpha^2 g(\mathcal{G}, \varphi \mathcal{H}) \zeta + \frac{1}{(n-1)} S(\mathcal{G}, \varphi \mathcal{H}) \zeta = 0.$$
(41)

Replace $\varphi \mathcal{H}$ by \mathcal{H} in (41) and on simplification, we get

$$S(\mathcal{G}, \mathcal{H})\zeta = -(n-1)\alpha^2 g(\mathcal{G}, \mathcal{H})\zeta. \tag{42}$$

By taking inner product with ζ in (42), we get

$$S(\mathcal{G}, \mathcal{H}) = -(n-1)\alpha^2 g(\mathcal{G}, \mathcal{H}). \tag{43}$$

Hence, we state the following theorem.

Theorem 5.1. If a Lorentzian α -Sasakian manifold satisfying $\varphi - W_1$ -semi-symmetric condition then the manifold is an Einstein Manifold.

6. LORENTZIAN α -SASAKIAN MANIFOLD SATISFYING $\mathcal{W}_1 \cdot \mathcal{Q} = 0$

In this section, we study the Lorentzian α -Sasakian manifold satisfying $W_1 \cdot Q = 0$. Then, we have

$$W_1(\mathcal{F}, \mathcal{G})\mathcal{QH} - \mathcal{Q}(W_1(\mathcal{F}, \mathcal{G})\mathcal{H}) = 0. \tag{44}$$

Putting $\mathcal{G} = \zeta$ in (44), we obtain

$$W_1(\mathcal{F}, \zeta)\mathcal{QH} - \mathcal{Q}(W_1(\mathcal{F}, \zeta)\mathcal{H}) = 0. \tag{45}$$

By virtue of (24) in (45), we get

$$R(\mathcal{F},\zeta)\mathcal{QH} + \frac{1}{(n-1)}[S(\zeta,\mathcal{QH})\mathcal{F} - S(\mathcal{F},\mathcal{QH})\zeta] - \mathcal{Q}\{R(\mathcal{F},\zeta)\mathcal{H} + \frac{1}{(n-1)}[S(\zeta,\mathcal{H})\mathcal{F} - S(\mathcal{F},\mathcal{H})\zeta]\} = 0.$$
(46)

By using (17), (19) in (46), we obtain

$$-\alpha^{2}[g(\mathcal{F},\mathcal{QH})\zeta - \eta(\mathcal{QH})\mathcal{F}] + \frac{1}{(n-1)}[S(\zeta,\mathcal{QH})\mathcal{F} - S(\mathcal{F},\mathcal{QH})\zeta]$$
$$-\mathcal{Q}\{-(\alpha^{2}[g(\mathcal{F},\mathcal{H})\zeta - \eta(\mathcal{H})\mathcal{F}] + \frac{1}{(n-1)}[S(\zeta,\mathcal{H})\mathcal{F} - S(\mathcal{F},\mathcal{H})\zeta]\} = 0, \quad (47)$$

$$-\alpha^{2}[S(\mathcal{F},\mathcal{H})\zeta - \eta(\mathcal{Q}\mathcal{H})\mathcal{F}] + \frac{1}{(n-1)}[2n\alpha^{2}\eta(\mathcal{Q}\mathcal{H})\mathcal{F} - S(\mathcal{F},\mathcal{Q}\mathcal{H})\zeta]$$
$$-\mathcal{Q}\{-\alpha^{2}g(\mathcal{F},\mathcal{H})\zeta + \alpha^{2}\eta(\mathcal{H})\mathcal{F} + \frac{1}{(n-1)}[2n\alpha^{2}\eta(\mathcal{H})\mathcal{F} - S(\mathcal{F},\mathcal{H})\zeta]\} = 0.$$
(48)

Using (20) and simplify (48), we have

$$S(\mathcal{F}, \mathcal{H})\zeta = 2n\alpha^2 g(\mathcal{F}, \mathcal{H})\zeta. \tag{49}$$

Taking inner product with ζ in (49), we have

$$S(\mathcal{F}, \mathcal{H}) = 2n\alpha^2 g(\mathcal{F}, \mathcal{H}). \tag{50}$$

Hence, we state the following theorem.

Theorem 6.1. A Lorentzian α -Sasakian manifold satisfying $W_1 \cdot Q = 0$, then the manifold is an Einstein manifold.

7. LORENTZIAN α -SASAKIAN MANIFOLD SATISFYING $\mathcal{W}_1 \cdot R = 0$.

In this section, we study the Lorentzian α -Sasakian manifold satisfying $W_1 \cdot R = 0$. Then, we have

$$W_1(\zeta, \mathcal{U})R(\mathcal{F}, \mathcal{G})\mathcal{H} - R(W_1(\zeta, \mathcal{U})\mathcal{F}, \mathcal{G})\mathcal{H} - R(\mathcal{F}, W_1(\zeta, \mathcal{U})\mathcal{G})\mathcal{H} - R(\mathcal{F}, \mathcal{G})W_1(\zeta, \mathcal{U})\mathcal{H} = 0.$$
 (51)

Putting $\mathcal{H} = \zeta$ in (51), we have

$$W_1(\zeta, \mathcal{U})R(\mathcal{F}, \mathcal{G})\zeta - R(W_1(\zeta, \mathcal{U})\mathcal{F}, \mathcal{G})\zeta - R(\mathcal{F}, W_1(\zeta, \mathcal{U})\mathcal{G})\zeta - R(\mathcal{F}, \mathcal{G})W_1(\zeta, \mathcal{U})\zeta = 0.$$
(52)

By using (16) in (52) and on simplification, we get

$$\alpha^2 \eta(\mathcal{W}_1(\zeta, \mathcal{U})\mathcal{F})\mathcal{G} - \alpha^2 \eta(\mathcal{W}_1(\zeta, \mathcal{U})\mathcal{G})\mathcal{F} - R(\mathcal{F}, \mathcal{G})\mathcal{W}_1(\zeta, \mathcal{U})\zeta = 0.$$
 (53)

By using (24) in (53), we get

$$\alpha^{2}\eta[R(\zeta,\mathcal{U})\mathcal{F} + \frac{1}{(n-1)}\{S(\mathcal{U},\mathcal{F})\zeta - S(\zeta,\mathcal{F}\}\mathcal{U}]\mathcal{G} - \alpha^{2}\eta[R(\zeta,\mathcal{U})\mathcal{G} + \frac{1}{(n-1)}\{S(\mathcal{U},\mathcal{G})\zeta - S(\zeta,\mathcal{G}\}\mathcal{U}]\mathcal{F} - R(\mathcal{F},\mathcal{G})[R(\zeta,\mathcal{U})\zeta + \frac{1}{(n-1)}\{S(\mathcal{U},\zeta)\zeta - S(\zeta,\zeta)\mathcal{U}\}] = 0.$$
(54)

By using (17), (19), (21) in (54) and on simplification, we get

$$\alpha^{2} \{ g(\mathcal{U}, \mathcal{F})\mathcal{G} - g(\mathcal{U}, \mathcal{G})\mathcal{F} \} + \frac{2n}{(n-1)}\alpha^{2}\eta(\mathcal{U})\eta(\mathcal{F})\mathcal{G} - \frac{2n}{(n-1)}\alpha^{2}\eta(\mathcal{U})\eta(\mathcal{G})\mathcal{F}$$
$$+ \frac{1}{(n-1)} \{ S(\mathcal{U}, \mathcal{G})\mathcal{F} - S(\mathcal{U}, \mathcal{F})\mathcal{G} \} + R(\mathcal{F}, \mathcal{G})\mathcal{U} = 0. \quad (55)$$

Putting $\mathcal{G} = \zeta$ in (55), we get

$$\alpha^{2} \{ g(\mathcal{U}, \mathcal{F}) \zeta - g(\mathcal{U}, \zeta) \mathcal{F} \} + \frac{2n}{(n-1)} \alpha^{2} \eta(\mathcal{U}) \{ \eta(\mathcal{F}) \zeta - \eta(\zeta) \mathcal{F} \}$$

$$+ \frac{1}{(n-1)} \{ S(\mathcal{U}, \zeta) \mathcal{F} - S(\mathcal{U}, \mathcal{F}) \zeta \} + R(\mathcal{F}, \zeta) \mathcal{U} = 0. \quad (56)$$

By using (9), (20), (22) in (56) and on simplification, we get

$$S(\mathcal{F}, \mathcal{U})\zeta = 2n\alpha^2 \eta(\mathcal{U})\eta(\mathcal{F})\zeta. \tag{57}$$

By taking inner product with ζ in (57), we have

$$S(\mathcal{F}, \mathcal{U}) = 2n\alpha^2 \eta(\mathcal{U})\eta(\mathcal{F}). \tag{58}$$

Hence, we state the following theorem.

Theorem 7.1. If a Lorentzian α -Sasakian manifold satisfying $W_1 \cdot R = 0$, then the manifold is a special type of η -Einstein manifold.

8. EXAMPLE OF A FIVE-DIMENSIONAL LORENTZIAN $\alpha\textsc{-}\mathrm{SASAKIAN}$ MANIFOLD

Consider a five dimensional manifold $M = \{(x, y, z, u, v) \in \mathbb{R}^5 : v \neq 0\}$, where (x, y, z, u, v) are the standard coordinates in \mathbb{R}^5 . We choose the vector fields

$$\varrho_1 = \varrho^v \frac{\partial}{\partial x}, \quad \varrho_2 = \varrho^v \frac{\partial}{\partial y}, \quad \varrho_3 = \varrho^v \frac{\partial}{\partial z}, \quad \varrho_4 = \varrho^v \frac{\partial}{\partial u}, \quad \varrho_5 = \alpha \frac{\partial}{\partial v},$$

which are linearly independent at each point of the manifold M. Let the Lorentzian metric g defined by

$$g(\varrho_{i}, \varrho_{j}) = \begin{cases} 1, & if \quad i = j \quad and \quad i, j \in \{1, 2, 3, 4\}, \\ -1, & if \quad i = j = 5, \\ 0, & otherwise. \end{cases}$$

and given by

$$g = \frac{1}{\rho^{2v}} \left[dx \otimes dx + dy \otimes dy + dz \otimes dz + du \otimes du - dv \otimes dv \right].$$

Let η be a 1-form which satisfies the relation

$$\eta(\varrho_5) = -1.$$

Let φ be a (1,1)-tensor field defined by $\varphi(\varrho_1) = -\varrho_2$, $\varphi(\varrho_3) = -\varrho_4$, $\varphi(\varrho_5) = 0$. Then, we have

$$\varphi^{2}(\mathcal{F}) = \mathcal{F} + \eta(\mathcal{F})\varrho_{5},$$
$$g(\varphi\mathcal{F}, \varphi\mathcal{G}) = g(\mathcal{F}, \mathcal{G}) + \eta(\mathcal{F})\eta(\mathcal{G}),$$

for any $\mathcal{F}, \mathcal{G} \in \chi(M^5)$. Thus for $\varrho_5 = \zeta$, $M^5(\varphi, \zeta, \eta, g)$ defines an almost contact metric structure on M. Now, we have

$$[\varrho_1, \varrho_2] = 0, \quad [\varrho_1, \varrho_3] = 0, \quad [\varrho_1, \varrho_4] = 0, \quad [\varrho_1, \varrho_5] = -\alpha \varrho_1, \quad [\varrho_2, \varrho_3] = 0,$$

$$[\varrho_2, \varrho_4] = 0, \quad [\varrho_2, \varrho_5] = -\alpha \varrho_2, \quad [\varrho_3, \varrho_4] = 0, \quad [\varrho_3, \varrho_5] = -\alpha \varrho_3, \quad [\varrho_4, \varrho_5] = -\alpha \varrho_4.$$

The Riemannian connection ∇ of the metric tensor g is given by the Koszul's formula

$$2g(\nabla_{\mathcal{F}}\mathcal{G},\mathcal{H}) = \mathcal{F}g(\mathcal{G},\mathcal{H}) + \mathcal{G}g(\mathcal{H},\mathcal{F}) - \mathcal{H}g(\mathcal{F},\mathcal{G}) - g(\mathcal{F},[\mathcal{G},\mathcal{H}]) - g(\mathcal{G},[\mathcal{F},\mathcal{H}]) + g(\mathcal{H},[\mathcal{F},\mathcal{G}]).$$

Taking $\varrho_5 = \zeta$ and using the Koszul's formula, we get the following

$$\begin{split} \nabla_{\varrho_1}\varrho_1 &= \alpha\varrho_1, \quad \nabla_{\varrho_2}\varrho_1 = 0, \quad \nabla_{\varrho_3}\varrho_1 = 0, \quad \nabla_{\varrho_4}\varrho_1 = 0, \quad \nabla_{\varrho_5}\varrho_1 = 0, \\ \nabla_{\varrho_1}\varrho_2 &= 0, \quad \nabla_{\varrho_2}\varrho_2 = \alpha\varrho_2, \quad \nabla_{\varrho_3}\varrho_2 = 0, \quad \nabla_{\varrho_4}\varrho_2 = 0, \quad \nabla_{\varrho_5}\varrho_2 = 0, \\ \nabla_{\varrho_1}\varrho_3 &= 0, \quad \nabla_{\varrho_2}\varrho_3 = 0, \quad \nabla_{\varrho_3}\varrho_3 = \alpha\varrho_3, \quad \nabla_{\varrho_4}\varrho_3 = 0, \quad \nabla_{\varrho_5}\varrho_3 = 0, \\ \nabla_{\varrho_1}\varrho_4 &= 0, \quad \nabla_{\varrho_2}\varrho_4 = 0, \quad \nabla_{\varrho_3}\varrho_4 = 0, \quad \nabla_{\varrho_4}\varrho_4 = \alpha\varrho_4, \quad \nabla_{\varrho_5}\varrho_4 = 0, \\ \nabla_{\varrho_1}\varrho_5 &= -\alpha\varrho_1, \quad \nabla_{\varrho_2}\varrho_5 = -\alpha\varrho_2, \quad \nabla_{\varrho_3}\varrho_5 = -\alpha\varrho_3, \quad \nabla_{\varrho_4}\varrho_5 = -\alpha\varrho_4, \quad \nabla_{\varrho_5}\varrho_5 = 0. \end{split}$$

Consequently, it is clear that M^5 satisfies the condition. These results shows that the manifold satisfies

$$\nabla_{\mathcal{F}}\zeta = -\alpha\varphi\mathcal{F},$$

for $\zeta = \varrho_5$. Hence the manifold under consideration is a Lorentzian α -Sasakian manifold of dimension five.

This manifold allows for the verification of the results stated in this article.

The components of the curvature tensor with respect to the Levi-Civita connection ∇ are as follows

$$\begin{split} R(\varrho_{1},\varrho_{2})\varrho_{1} &= -\alpha^{2}\varrho_{2}, \quad R(\varrho_{1},\varrho_{2})\varrho_{2} = \alpha^{2}\varrho_{1}, \quad R(\varrho_{1},\varrho_{3})\varrho_{1} = -\alpha^{2}\varrho_{3}, \\ R(\varrho_{1},\varrho_{3})\varrho_{3} &= \alpha^{2}\varrho_{1}, \quad R(\varrho_{1},\varrho_{4})\varrho_{1} = -\alpha^{2}\varrho_{4}, \quad R(\varrho_{1},\varrho_{4})\varrho_{4} = \alpha^{2}\varrho_{1}, \\ R(\varrho_{1},\varrho_{5})\varrho_{1} &= -\alpha^{2}\varrho_{5}, \quad R(\varrho_{1},\varrho_{5})\varrho_{5} = -\alpha^{2}\varrho_{1}, \quad R(\varrho_{2},\varrho_{3})\varrho_{2} = -\alpha^{2}\varrho_{3}, \\ R(\varrho_{2},\varrho_{3})\varrho_{3} &= \alpha^{2}\varrho_{2}, \quad R(\varrho_{2},\varrho_{4})\varrho_{2} = -\alpha^{2}\varrho_{4}, \quad R(\varrho_{2},\varrho_{4})\varrho_{4} = \alpha^{2}\varrho_{2}, \\ R(\varrho_{2},\varrho_{5})\varrho_{2} &= -\alpha^{2}\varrho_{5}, \quad R(\varrho_{2},\varrho_{5})\varrho_{5} = -\alpha^{2}\varrho_{2}, \quad R(\varrho_{3},\varrho_{4})\varrho_{3} = -\alpha^{2}\varrho_{4}, \\ R(\varrho_{3},\varrho_{4})\varrho_{4} &= \alpha^{2}\varrho_{3}, \quad R(\varrho_{3},\varrho_{5})\varrho_{3} = -\alpha^{2}\varrho_{5}, \quad R(\varrho_{3},\varrho_{5})\varrho_{5} = -\alpha^{2}\varrho_{3}, \\ R(\varrho_{4},\varrho_{5})\varrho_{4} &= -\alpha^{2}\varrho_{5}, \quad R(\varrho_{4},\varrho_{5})\varrho_{5} = -\alpha^{2}\varrho_{4}. \end{split}$$

From the previous results, we can obtain the Ricci tensor S of the Levi-Civita connection ∇ , which is as follows: $S(\varrho_1,\varrho_1)=4\alpha^2, \quad S(\varrho_2,\varrho_2)=4\alpha^2, \quad S(\varrho_3,\varrho_3)=4\alpha^2, \quad S(\varrho_4,\varrho_4)=4\alpha^2, \\ S(\varrho_5,\varrho_5)=-4\alpha^2.$ The scalar curvature r with respect to the Levi-Civita connection ∇ is given by $r=\sum_{i=1}^5 S(\varrho_i,\varrho_i)=20\alpha^2.$

9. CONCLUDING REMARKS

In this paper, we introduce the concepts of W_1 -flat and $\zeta - W_1$ -flat Lorentzian α -Sasakian manifolds, which were identified as special types of η -Einstein manifolds. We also explored the $\varphi - W_1$ -semi-symmetric condition in Lorentzian α -Sasakian manifolds, discovering that it results in an Einstein manifold. Furthermore, we examined Lorentzian α -Sasakian manifolds that satisfy the condition $W_1 \cdot Q = 0$, establishing that they are also Einstein manifolds. Finally, we discuss Lorentzian α -Sasakian manifolds that meet the condition $W_1 \cdot R = 0$, concluding that they are η -Einstein manifolds.

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